

Multifunctional damper actuator for adjusting air dampers in ventilation and air-conditioning systems for building services installations

- For air dampers up to approx. 4 m²
- Torque 20 Nm
- Nominal voltage AC/DC 24 V
- Control: Modulating DC 0 ... 10 V or variable
- Position feedback DC 2 ... 10 V or variable
- Communication via BELIMO MP-Bus
- Conversion of sensor signals



Technical data

Electrical data

Nominal voltage	AC 24 V, 50/60 Hz / DC 24 V	
Nominal voltage range	AC 19.2 ... 28.8 V / DC 21.6 ... 28.8 V	
Power consumption	In operation At rest For wire sizing	4 W @ nominal torque 1.25 W 6 VA
Connection	Cable 1 m, 4 x 0.75 mm ²	

Functional data	Factory settings	Variable	Settings
Torque (nominal torque)	Min. 20 Nm @ nominal voltage	25%, 50%, 75% reduziert
Control	Control signal Y	Open-close, 3-point (AC only), modulating (DC 0 ... 32 V)
	Operating range	DC 2 ... 10 V	Start point DC 0.5 ... 30 V End point DC 2.5 ... 32 V
Position feedback (Measuring voltage U)	DC 2 ... 10 V, max. 0.5 mA	Start point DC 0.5 ... 8 V End point DC 2.5 ... 10 V

Position accuracy	±5%		
Direction of rotation	Reversible with switch 0 / 1		
Direction of motion at Y = 0 V	In switch position 0 ↗ resp. 1 ↘	Electronically reversible
Manual override	Gearing latch disengaged with pushbutton, can be locked		
Angle of rotation	Max. 95° ↗, can be limited at both ends with adjustable mechanical end stops		
Running time	150 s / 90° ↗	86 ... 346 s
Automatic adjustment running time, operating range and measuring signal U to match the mechanical angle of rotation	Manual triggering of the adaption by pressing the «Adaption» button or with the PC-Tool	Automatic adaption whenever the supply voltage is switched on, or manual triggering
Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%	MAX = (MIN + 30° ↗) ... 100% MIN = 0% ... (MAX - 30° ↗) ZS = MIN ... MAX
Sound power level	Max. 45 dB (A)	With a 86 s = 45 dB (A) running time 346 s = <35 dB (A)	

Position indication	Mechanical, pluggable
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Safety

Protection class	III Safety extra-low voltage / UL Class 2 Supply
Degree of protection	IP54 in any mounting position NEMA 2, UL Enclosure Type 2
EMC	CE according to 2004/108/EC
Certification	cULus according to UL 60730-1A and UL 60730-2-14 and CAN/CSA E60730-1:02 Certified to IEC/EN 60730-1 and IEC/EN 60730-2-14
Mode of operation	Type 1
Rated impulse voltage	0.8 kV
Control pollution degree	3
Ambient temperature	-30 ... +50°C
Non-operating temperature	-40 ... +80°C
Ambient humidity	95% r.h., non-condensating
Maintenance	Maintenance-free

Technical data*(Continued)***Dimensions / Weight**

Dimensions	See «Dimensions» on page 5
Weight	ca. 920 g

Safety notes

- The actuator is not allowed to be used outside the specified field of application, especially in aircraft or any other form of air transport.
- Assembly must be carried out by trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The cable must not be removed from the device.
- When calculating the required torque, the specifications supplied by the damper manufacturers (cross section, design, installation site), and the air flow conditions must be observed.
- The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features**Mode of operation**

Conventional operation: The actuator is controlled with a standard modulating signal of DC 0 ... 10 V and travels to the position defined by the control signal. Measuring voltage U serves for the electrical display of the damper position 0 ... 100% and as slave control signal for other actuators.

Operation on the MP-Bus: The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and travels to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Parameterisable actuators

The factory settings cover the most common applications. Input and output signals and other parameters can be altered with the MFT-H parameterising device or the BELIMO Service Tool, MFT-P.

Simple direct mounting

Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an anti-rotation strap to prevent the actuator from rotating.

Manual override

Manual operation is possible with the pushbutton (the gearing latch remains disengaged as long as the pushbutton is pressed or detented).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.

Home position

When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing the «gear disengagement» switch, the actuator travels to the home position.

Pos. direction of rotation switch	Home position
	ccw Left stop
	cw Right stop

The actuator then moves into the position defined by the control signal.

Accessories**Description****Data sheet****Electrical accessories**

Auxiliary switch S..A..

T2 - S..A..

Feedback potentiometer P..A..

T2 - P..A..

PC-Tool MFT-P from version 3.3

T2 - MFT-P

Parameterising device MFT-H

T2 - MFT-H

Position sensor SGA24, SGE24 and SGF24 (only in conventional mode)

T2 - SG..24

Digital position indication ZAD24

T2 - ZAD24

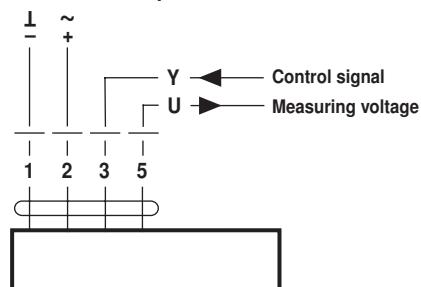
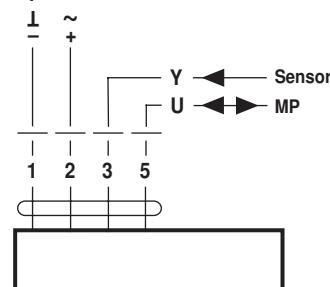
Mechanical accessories

Various accessories (clamps, shaft extensions etc.)

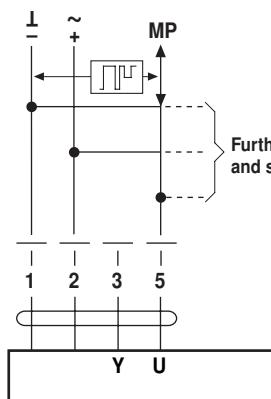
T2 - Z-SM..A..

Electrical installation**Wiring diagrams****Notes**

- Connection via safety isolating transformer! 
- Other actuators can be connected in parallel. Please note the performance data!

Conventional operation**Operation on the MP-Bus**

Cable colours:
1 = black
2 = red
3 = white
5 = orange

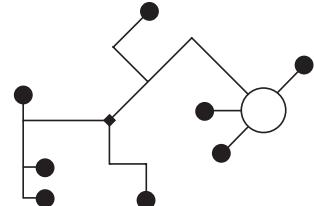
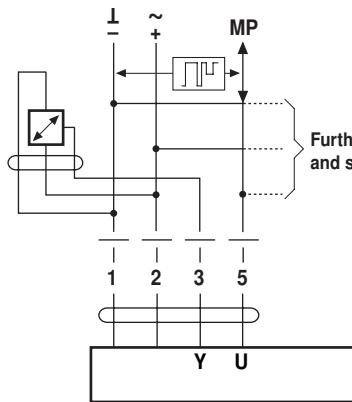
Functions when operated on MP-Bus**Connection on the MP-Bus****Supply and communication**

in one and the same 3-wire cable

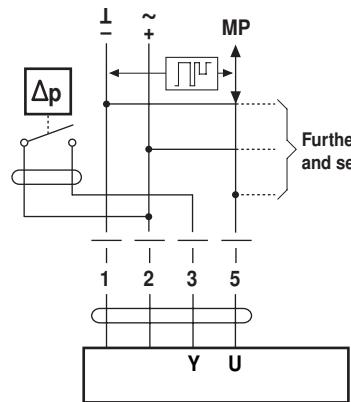
- no shielding or twisting necessary
- no terminating resistors required

Power topology

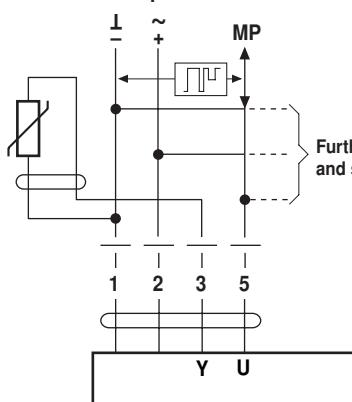
There are no restrictions for the network topology (star, ring, tree or hybrid forms are permitted).

**Connection of active sensors**

- Supply AC/DC 24 A
- Output signal DC 0 ... 10 V (max. DC 0 ... 32 V)
- Resolution 30 mV

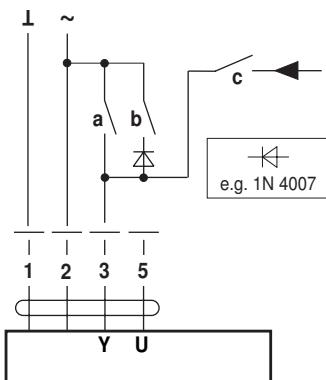
Connection of external switching contact

- Switching current 16 mA @ 24 V
- Start point of the operating range must be parameterised on the MP actuator as ≥ 0.6 V

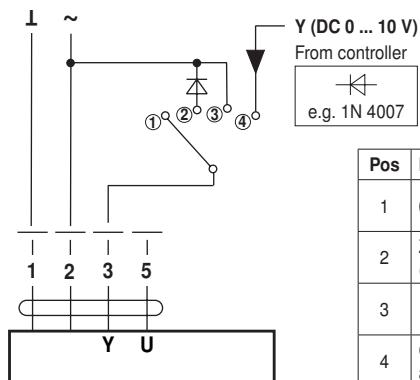
Connection of passive sensors

Sensor	Temperature range	Resistance range	Resolution
Ni1000	-28 ... +98°C	850 ... 1600 Ω	1 Ω
PT1000	-35 ... +155°C	850 ... 1600 Ω	1 Ω
NTC	-10 ... +160°C (depending on type)	200 Ω ... 60 kΩ	1 Ω

Functions with basic values (only in conventional mode)

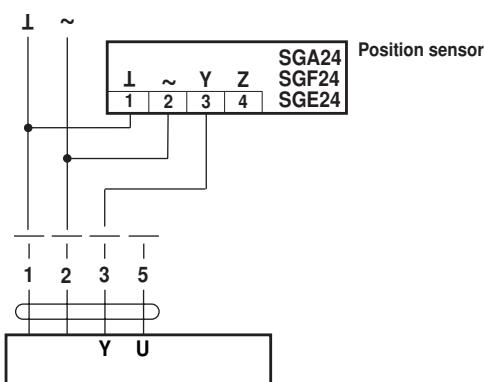
Override control with AC 24 V
with relay contacts

Functions	a	b	c
0%	/	-	-
ZS 50% (intermediate position)	/	-	-
100%	-	/	-
Control mode in accordance with Y	/	-	/

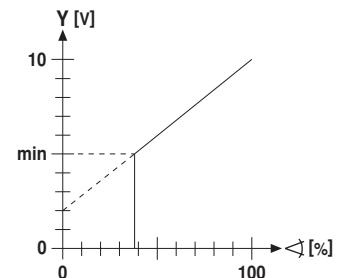
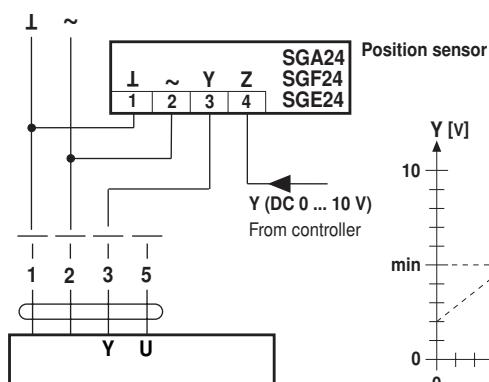
Override control with AC 24 V
with rotary control switch

Pos	Functions
1	0%
2	ZS 50% (intermediate position)
3	100%
4	Control mode in accordance with Y

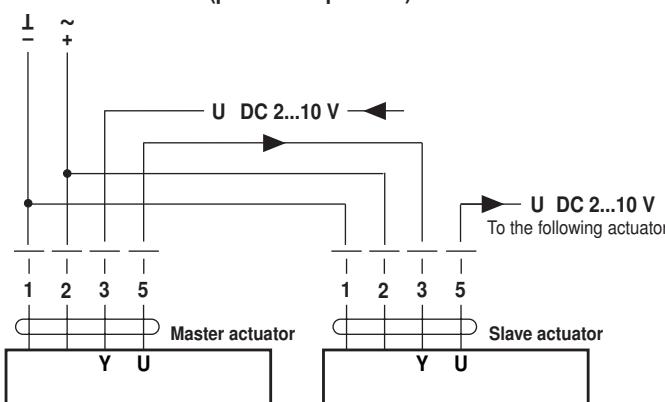
Remote control 0 ... 100%



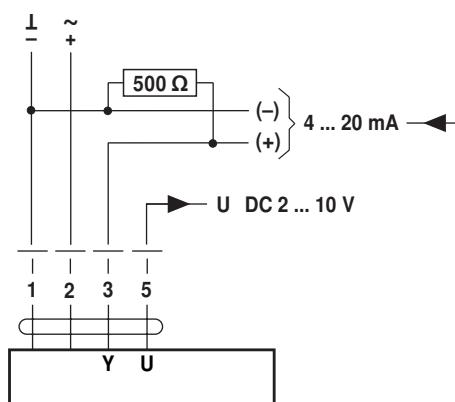
Minimum limit



Master/Slave control (position-dependent)

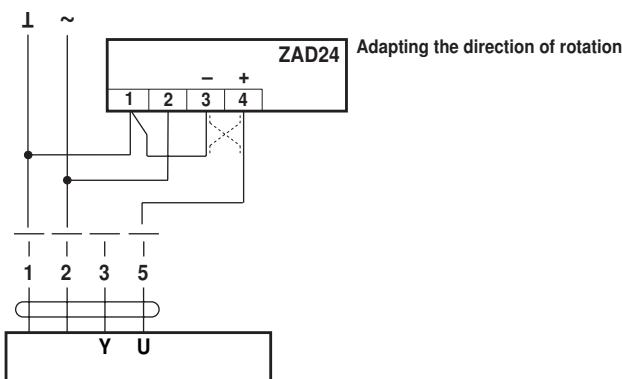


Control with 4 ... 20 mA via external resistance

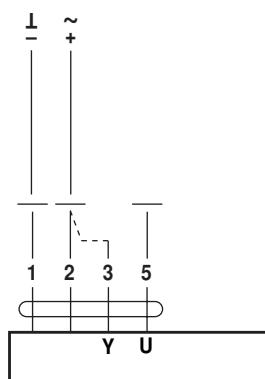


The 500 Ω resistor converts the
4 ... 20 mA current signal to a
voltage signal DC 2 ... 10 V

Position indication



Functional check

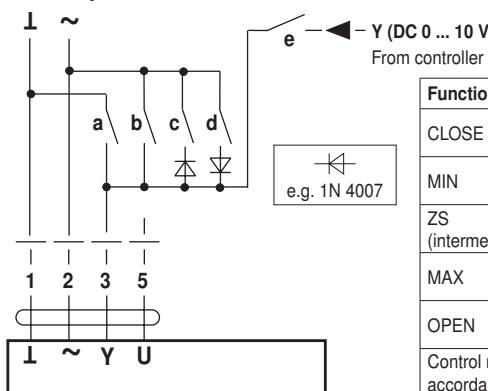


Procedure

- Apply 24 V to connection 1 and 2
- Disconnect connection 3:
 - For direction of rotation 0:
Actuator turns in the direction of ↘
 - For direction of rotation 1:
Actuator turns in the direction of ↗
- Short circuit connections 2 and 3:
 - Actuator travels in the opposite direction

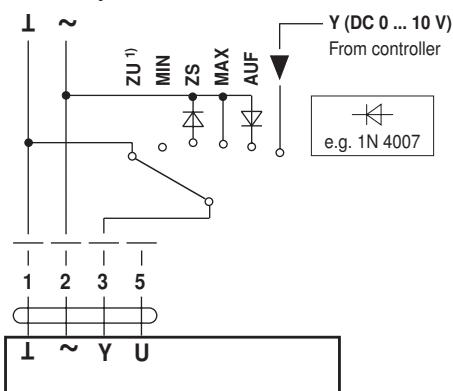
Functions for actuators with specific parameters

Override control and limiting with AC 24 V
with relay contacts



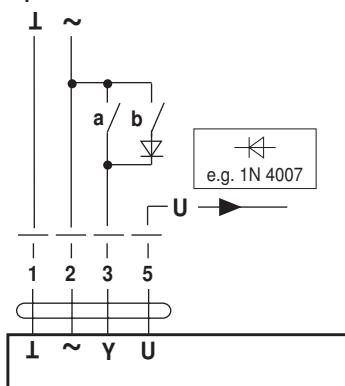
Functions	a	b	c	d	e
CLOSE ¹⁾	—	—	—	—	—
MIN	—	—	—	—	—
ZS (intermediate position)	—	—	—	—	—
MAX	—	—	—	—	—
OPEN	—	—	—	—	—
Control mode in accordance with Y	—	—	—	—	—

Override control and limiting with AC 24 V
with rotary switch



¹⁾ Caution ! This function is only guaranteed if the start point of the operating range is defined as min. 0.6 V

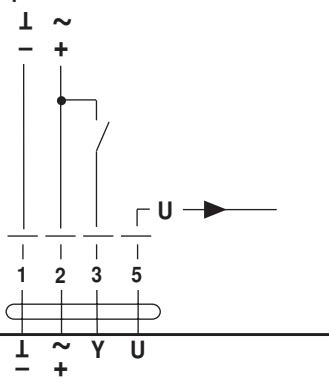
3-point control



Direction of rotation switch

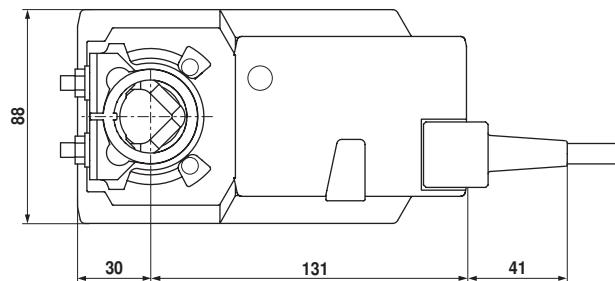
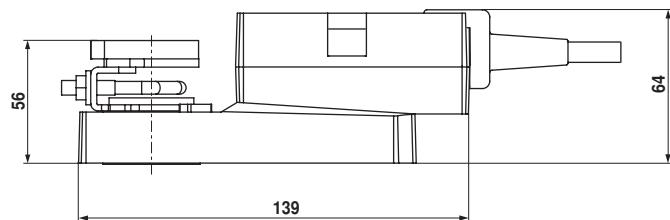
a	b	0	1
—	—	—	—
—	—	stop	stop
—	—	—	—
—	—	—	—

Open-close control



Dimensions [mm]

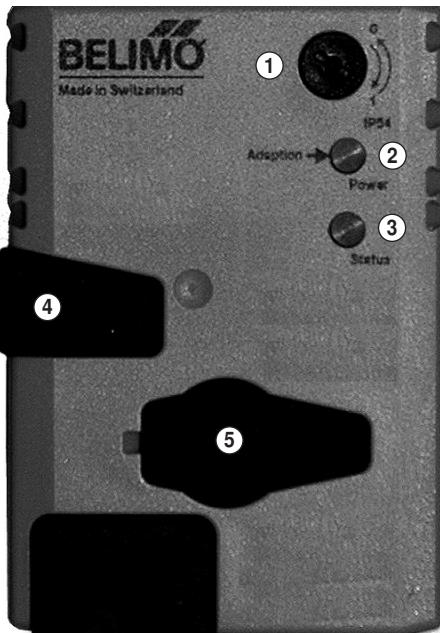
Dimensional drawings



Damper spindle	Length			
	≥48	10 ... 20 ¹⁾	≥10	≤20
	≥20	10 ... 20 ¹⁾	≥10	≤20

¹⁾ CrNi (INOX) 12 ... 20

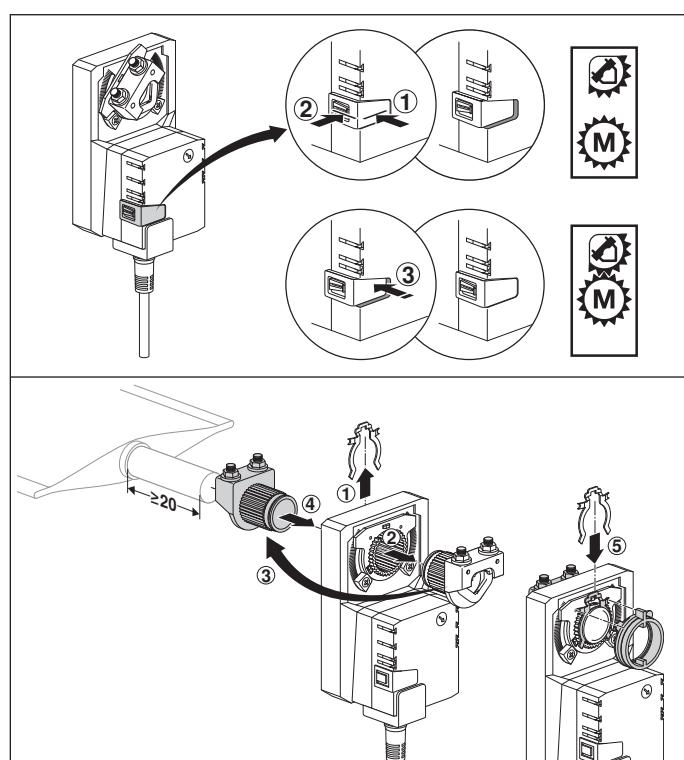
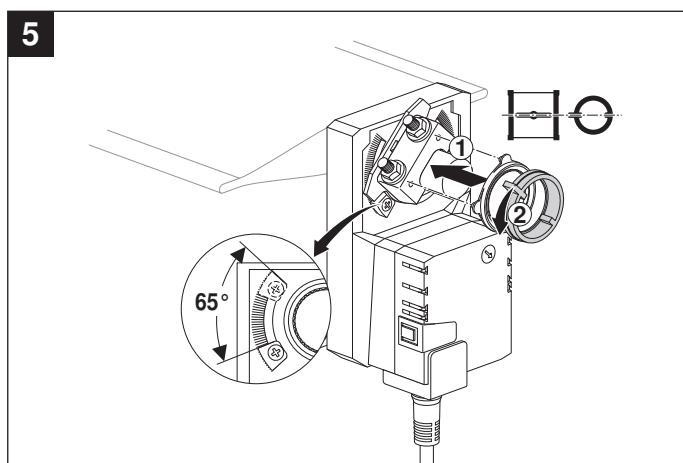
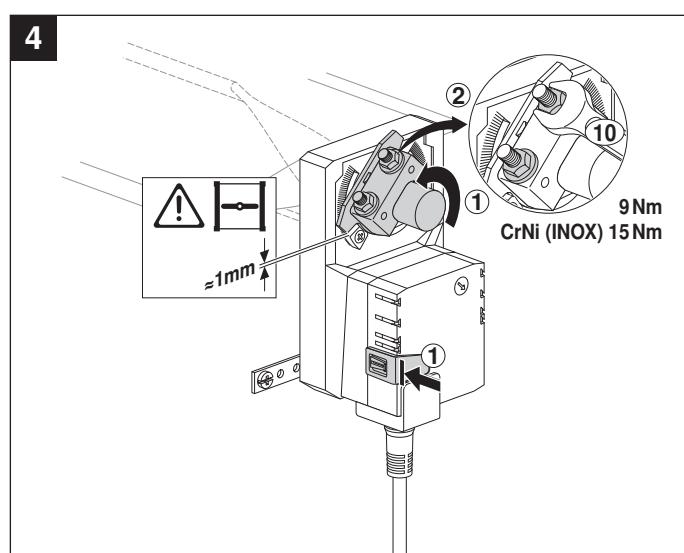
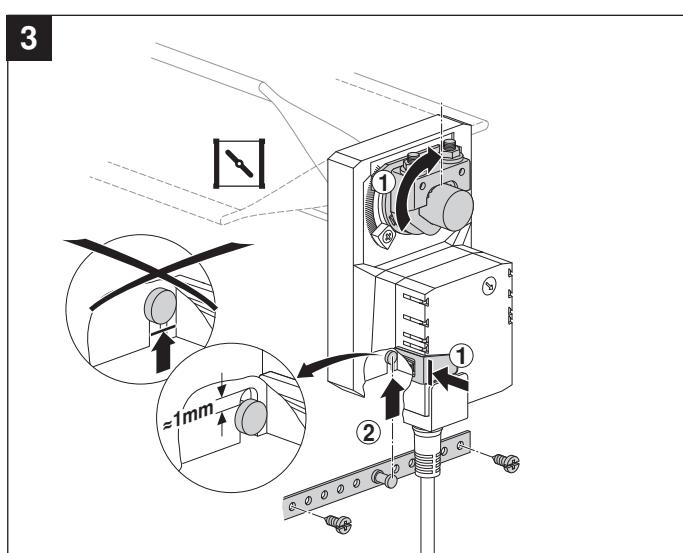
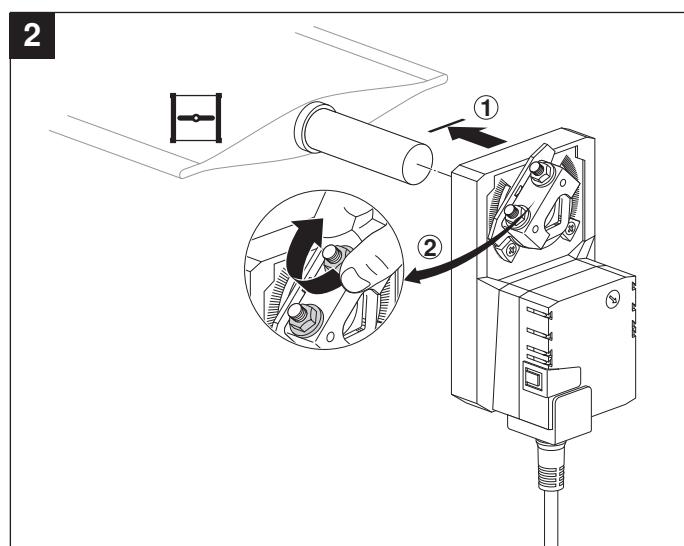
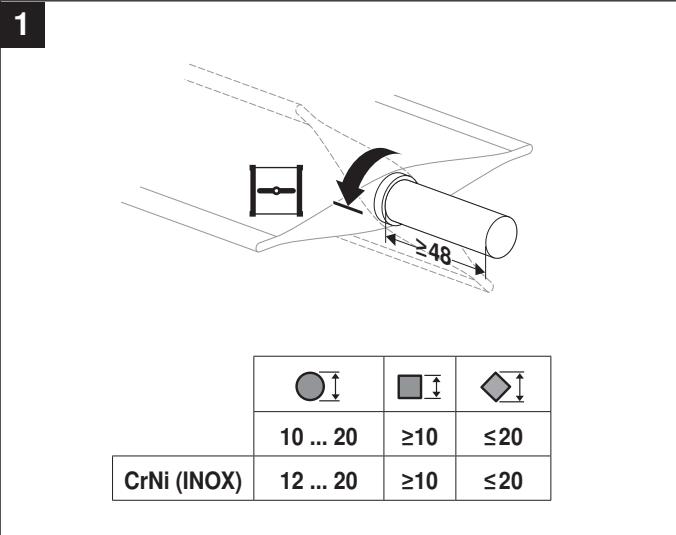
Operating controls and indicators

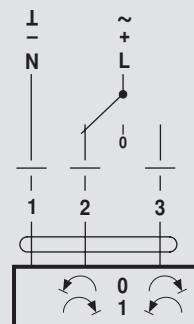
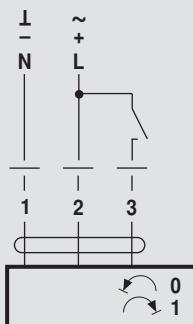


- ① **Direction of rotation switch**
Switching over: Direction of rotation changes
- ② **Pushbutton and green LED display**
Off: No voltage supply or malfunction
On: Operation
Press button: Switches on angle of rotation adaption followed by standard operation
- ③ **Pushbutton and yellow LED display**
Off: Standard operation without MP bus
On: Adaption or synchronising process active
Blinking: Addressing request sent to MP master
Press button: Acknowledgment of addressing
Flickering: MP communication active
- ④ **Gear disengagement switch**
Press button: Gear disengaged, motor stops, manual operation possible
Release button: Gear engaged, synchronisation starts, followed by standard operation
- ⑤ **Service plug**
For connecting parameterising and service tools

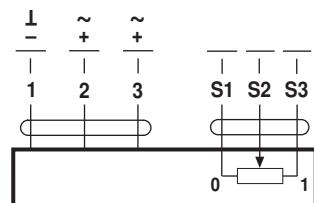
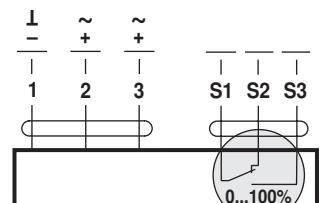
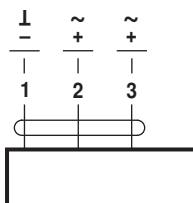
Check voltage supply connection

- a) ② Off and ③ On } Check the supply connections.
- b) ② Blinking and ③ Blinking } Possibly \perp and \mp are swapped over.





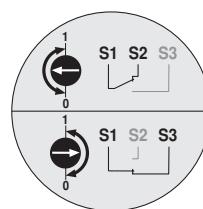
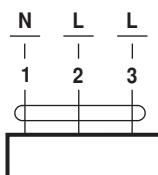
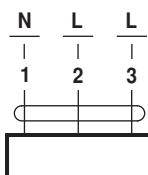
AC 24 V / DC 24 V

SM24A..
SMD24A..

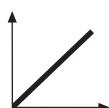
SM24A-S..

SM24AP5..

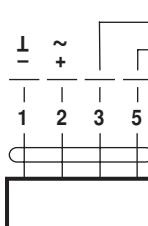
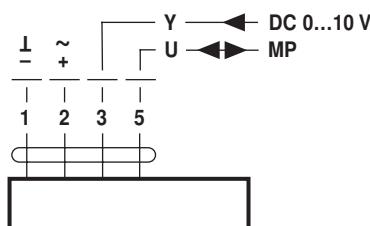
AC 100 ... 240 V

SM230A..
SMD230A..

SM230A-S..

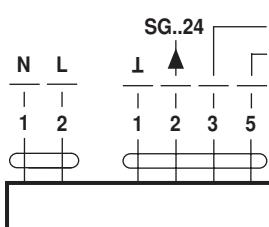


AC 24 V / DC 24 V

SM24A-SR..
SM24A-MF..

SM24A-MP..

AC 100 ... 240 V



SM230ASR..

AC 24 V / DC 24 V
(SM24A-V / VR..)