

Brushless DC-Servomotors

2 Pole Technology

190 mNm

232 W

Series 4490 ... B

Values at 22°C and nominal voltage		4490 H	024 B	036 B	048 B	
1	Nominal voltage	U_N	24	36	48	V
2	Terminal resistance, phase-phase	R	0,22	0,44	0,7	Ω
3	Efficiency, max.	η_{max}	87	87	87	%
4	No-load speed	n_0	9 700	10 400	10 800	min ⁻¹
5	No-load current, typ. (with shaft ø 6 mm)	I_0	0,527	0,397	0,317	A
6	Stall torque	M_H	2 635	2 760	2 978	mNm
7	Friction torque, static	C_0	4,96	4,96	4,96	mNm
8	Friction torque, dynamic	C_V	$7,72 \cdot 10^{-4}$	$7,72 \cdot 10^{-4}$	$7,72 \cdot 10^{-4}$	mNm/min ⁻¹
9	Speed constant	k_n	395	283	220	min ⁻¹ /V
10	Back-EMF constant	k_E	2,53	3,54	4,56	mV/min ⁻¹
11	Torque constant	k_M	24,2	33,8	43,5	mNm/A
12	Current constant	k_I	0,041	0,03	0,023	A/mNm
13	Slope of n-M curve	$\Delta n / \Delta M$	3,6	3,7	3,5	min ⁻¹ /mNm
14	Terminal inductance, phase-phase	L	73	142	235	μ H
15	Mechanical time constant	τ_m	4,9	5	4,8	ms
16	Rotor inertia	J	130	130	130	gcm ²
17	Angular acceleration	α_{max}	203	212	229	$\cdot 10^3$ rad/s ²
18	Thermal resistance	R_{th1} / R_{th2}	0,96 / 3,9			K/W
19	Thermal time constant	τ_{w1} / τ_{w2}	23 / 1 222			s
20	Operating temperature range:					
	– motor		-30 ... +125			°C
	– winding, max. permissible		+125			°C
21	Shaft bearings		ball bearings, preloaded			
22	Shaft load max.:					
	– with shaft diameter		6			mm
	– radial at 3 000 min ⁻¹ (5 mm from mounting flange)		113			N
	– axial at 3 000 min ⁻¹ (push only)		45			N
	– axial at standstill (push only)		135			N
23	Shaft play:					
	– radial	≤	0,015			mm
	– axial	=	0			mm
24	Housing material		aluminium, black anodized			
25	Mass		742			g
26	Direction of rotation		electronically reversible			
27	Speed up to	n_{max}	18 000			min ⁻¹
28	Number of pole pairs		1			
29	Hall sensors		digital			
30	Magnet material		NdFeB			
Rated values for continuous operation						
31	Rated torque	M_N	148	139	137	mNm
32	Rated current (thermal limit)	I_N	7,45	5,06	3,91	A
33	Rated speed	n_N	9 650	10 470	10 930	min ⁻¹

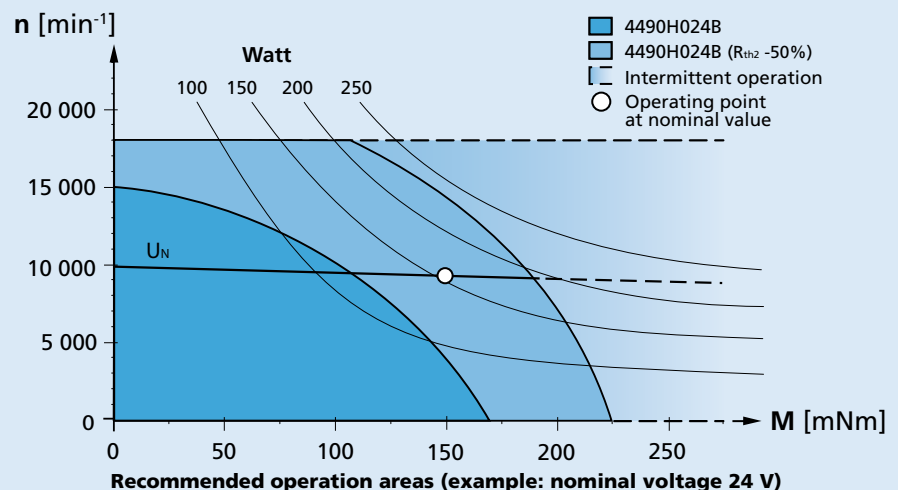
Note: Rated values are calculated with nominal voltage and at a 22°C ambient temperature. The R_{th2} value has been reduced by 25%.

Note:

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

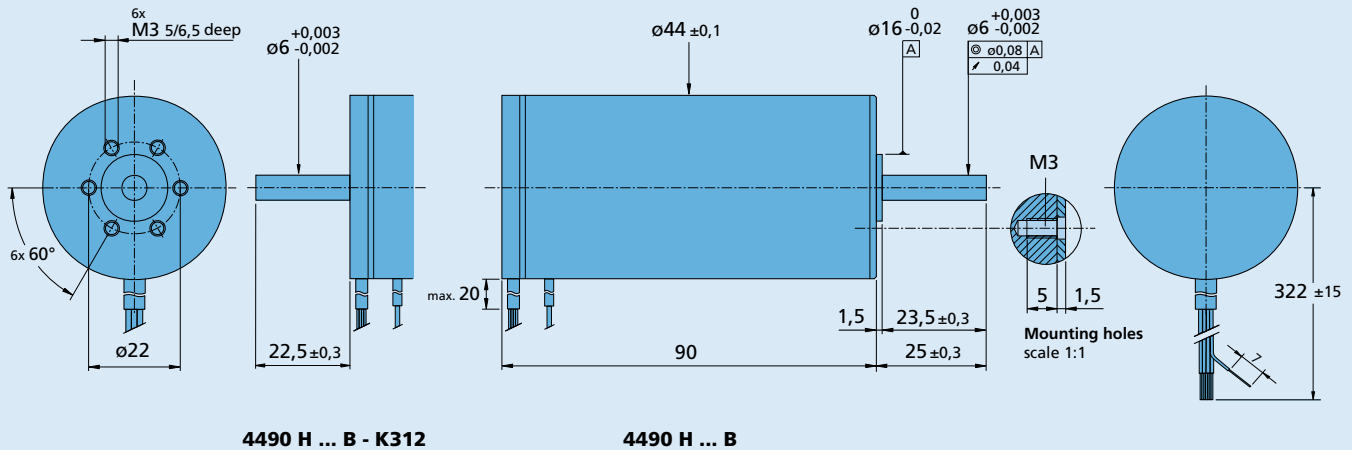
The diagram shows the motor in a completely insulated as well as thermally coupled condition (R_{th2} 50% reduced).

The nominal voltage (U_N) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.



Dimensional drawing

Scale reduced 



Option, cable and connection information

Example product designation: **4490H024B-K1155**

Option	Type	Description	Connection	
			Function	Colour
K1155	Controller combination	Analog Hall sensors for combination with Motion Controller MCBL	Phase C	yellow
K1026	Sensorless	Motor without Hall sensors	Phase B	orange
K1838	Encoder combination	Motor with rear end shaft for combination with Encoder IE3	Phase A	brown
K312	Encoder combination	Motor with rear end shaft for combination with Encoder HEDS/HEDL/HEDM	GND	black
K3051	Encoder combination	Motor with rear end shaft for combination with Encoder AES	U _{DD} (+5V)	red
K179	Bearing lubrication	For vacuum of 10 ⁻⁵ Pa @ 22°C	Hall sensor C	grey
			Hall sensor B	blue
			Hall sensor A	green
			Standard cable	
			Single wires, material PTFE	
			AWG 16: Phase A/B/C	
			AWG 26: Hall A/B/C, U _{DD} , GND	

Product combination

Precision Gearheads / Lead Screws	Encoders	Drive Electronics	Cables / Accessories
38A 42GPT 44/1	HEDS 5500 IE3-1024 IE3-1024 L HEDL 5540 AES-4096 AES-4096 L	SC 5004 P SC 5008 S MCBL 3006 S MC 5010 S	MBZ To view our large range of accessory parts, please refer to the "Accessories" chapter.