

Motion Controllers

V2.5, 4-Quadrant PWM
with RS232 or CAN interface

MCBL 3006 S AES

| Values at 22°C | MCBL 3006 S AES | |
|------------------------------------------------|-----------------|--------------------|
| Power supply electronic | U_B/U_{EL} | 12 ... 30 V DC |
| Power supply motor ¹⁾ | $-/U_B$ | 0 ... 30 V DC |
| PWM switching frequency | f_{PWM} | 78,12 kHz |
| Efficiency electronic | η | 95 % |
| Max. continuous output current | I_{cont} | 6 A |
| Max. peak output current ²⁾ | I_{max} | 10 A |
| Standby current for electronic (at $U_B=24V$) | I_{el} | 0,06 A |
| Operating temperature range | | -40 ... +85 °C |
| Housing material | | zinc, black coated |
| Mass | | 160 g |

¹⁾ Only available for option 3085 (separate power supply)

²⁾ S2 mode for max. 9s

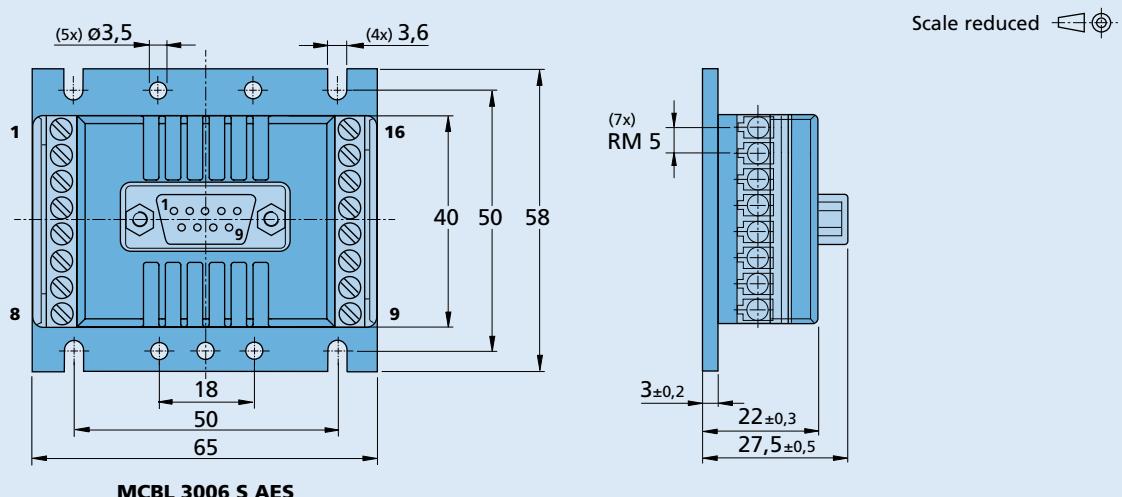
| Interfaces | MCBL 3006 S AES RS | MCBL 3006 S AES CO |
|------------|--------------------|--------------------|
| Interface | RS232 | CAN (CiA) |
| Protocol | FAULHABER - ASCII | CANopen |

Basic features

- Supported sensor systems: single-turn absolute encoders
- Positioning resolution when using absolute encoders as position encoder: 4096 steps per revolution
- Max. 3 digital inputs, max. 1 digital output, 1 analog input.
Not all I/Os available depending on wiring
- Setpoint specification via fieldbus, quadrature signal, pulse and direction or analog inputs
- Optional stand-alone operation via application programs with the RS232 interface version

Range of functions

| | |
|--------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Operating modes (RS Versions) | Position, speed and torque control with setpoint specification via interface or analog. Position control with Gearing Mode or stepper motor operation. Operation as Servo Amplifier in voltage controller mode |
| Operating modes (CO Version) | Profile Position Mode (PP), Profile Velocity Mode (PV), Homing Mode. |
| Speed range for brushless motors with number of pole pairs 1 | 5 min ⁻¹ ... 30 000 min ⁻¹ (with sinus commutation) |
| Application programs | Available in versions with RS232 interface |
| Additional functions | Overload protection for electronics and motor, self-protection from overheating, over-voltage protection in generator mode. |
| Indicator | Trace as logger |
| Motor types | Brushless DC-motors with absolute encoders and number of pole pairs 1 or 2 |

Dimensional drawing

Options and connection information

Example product designation: **MCBL 3006 S AES RS 3085**

| Option | Type | Description | Connection | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|--------|-------------|-------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|----------|-----|----------|---|-------------|---|-----------------|---|-------------|----|---------------|---|------|----|----------------|---|-------|----|-------|---|------|----|------|---|----|----|---------|---|-----|----|---------|---|-------|----|---------|
| 3085 | Supply | Separate power supply for motor and electronics | <table border="1"> <thead> <tr> <th>No.</th><th>Function</th><th>No.</th><th>Function</th></tr> </thead> <tbody> <tr><td>1</td><td>TxD / CAN_H</td><td>9</td><td>Sensor A / DATA</td></tr> <tr><td>2</td><td>RxD / CAN_L</td><td>10</td><td>Sensor B / CS</td></tr> <tr><td>3</td><td>AGND</td><td>11</td><td>Sensor C / CLK</td></tr> <tr><td>4</td><td>Fault</td><td>12</td><td>Ucc</td></tr> <tr><td>5</td><td>AnIn</td><td>13</td><td>SGND</td></tr> <tr><td>6</td><td>Ub</td><td>14</td><td>Motor A</td></tr> <tr><td>7</td><td>GND</td><td>15</td><td>Motor B</td></tr> <tr><td>8</td><td>3. In</td><td>16</td><td>Motor C</td></tr> </tbody> </table> | No. | Function | No. | Function | 1 | TxD / CAN_H | 9 | Sensor A / DATA | 2 | RxD / CAN_L | 10 | Sensor B / CS | 3 | AGND | 11 | Sensor C / CLK | 4 | Fault | 12 | Ucc | 5 | AnIn | 13 | SGND | 6 | Ub | 14 | Motor A | 7 | GND | 15 | Motor B | 8 | 3. In | 16 | Motor C |
| No. | Function | No. | Function | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | TxD / CAN_H | 9 | Sensor A / DATA | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | RxD / CAN_L | 10 | Sensor B / CS | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | AGND | 11 | Sensor C / CLK | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | Fault | 12 | Ucc | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | AnIn | 13 | SGND | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | Ub | 14 | Motor A | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | GND | 15 | Motor B | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | 3. In | 16 | Motor C | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | D-SUB connector | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | RS-232 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | CAN | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
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| No. | Function | No. | Function | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | RxD | 2 | CAN_L | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | TxD | 3 | GND | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | GND | 5 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | - | 7 | CAN_H | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | Note: For details on the connection assignment, see device manual MC. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Product combination

| | |
|--------------------------------------------------------------|----------------------------------------------------------------------------------------|
| Brushless DC-Motors | Cables / Accessories |
| 2232 ... BX4 2250 ... BX4 3242 ... BX4 3268 ... BX4 | To view our large range of accessory parts, please refer to the „Accessories“ chapter. |